

4. Computation Tree Logic (1)

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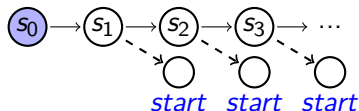
Outline

- 1 Syntax
- 2 Semantics
- 3 Equivalence of CTL Formulae
- 4 Normal Forms for CTL
- 5 Expressiveness of CTL and LTL
- 6 CTL Model Checking

1 Syntax

Properties for **some** or **all** computations that start in a state

- 1 existential path quantifier (\exists),
 $\exists \diamond \Phi$: there is at least one possible computation in which a state that satisfies Φ is eventually reached
- 2 a universal path quantifier (denoted \forall),
 $\forall \diamond \Phi$: all computations satisfy the property $\diamond \Phi$
- 3 nesting universal and existential path quantifiers, $\forall \square \exists \diamond start$:



- for every computation it is always possible to return to the initial state
- in any state (\square) of any possible computation (\forall), there is a possibility (\exists) to eventually return to the start state ($\diamond start$)

1 Syntax

$$\text{CTL} \begin{cases} \Phi ::= \text{true} \mid a \mid \Phi_1 \wedge \Phi_2 \mid \neg\Phi \mid \exists\varphi \mid \forall\varphi & \text{state formulae} \\ \varphi ::= \bigcirc\Phi \mid \Phi_2 \mathbf{U}\Phi_1 & \text{path formulae} \end{cases}$$

- 1 state formulae express a property of a state
- 2 path formulae express a property of a path
- 3 $\exists\varphi$ holds in a state s if \exists path satisfying φ that starts in s
- 4 $\forall\varphi$ holds in a state s if all paths that start in s satisfy φ .

1 Syntax

$$\exists\Diamond\Phi = \exists(\text{true}\mathbf{U}\Phi)$$

Φ holds potentially

$$\forall\Diamond\Phi = \forall(\text{true}\mathbf{U}\Phi)$$

Φ is inevitable

$$\exists\Box\Phi = \neg\forall\Diamond\neg\Phi$$

potentially always Φ

$$\forall\Box\Phi = \neg\exists\Diamond\neg\Phi$$

invariantly Φ

- $\exists\neg\Diamond\neg\Phi$ is not a CTL formula
- Mutual exclusion property can be described in CTL by the formula $\forall\Box(\neg\text{crit}_1 \vee \neg\text{crit}_2)$
- The traffic light is infinitely often green: $\forall\Box\forall\Diamond\text{green}$

$\forall\Box\forall\Diamond\text{green}$

versus

$\forall\Diamond\text{green}$

- “Every request will eventually be granted” can be described by $\forall\Box(\text{request} \rightarrow \forall\Diamond\text{response})$

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Satisfaction Relation for CTL

Let $a \in AP$, $TS = (S, Act, \rightarrow, I, AP, L)$, $s \in S$, Φ, Ψ be CTL state formulae, and φ be a CTL path formula.

① The satisfaction relation \models is defined for **state formulae** by

$$s \models a \quad \text{iff} \quad a \in L(s)$$

$$s \models \neg\Phi \quad \text{iff} \quad \text{not } s \models \Phi$$

$$s \models \Phi \wedge \Psi \quad \text{iff} \quad (s \models \Phi) \text{ and } (s \models \Psi)$$

$$s \models \exists\varphi \quad \text{iff} \quad \pi \models \varphi \text{ for some } \pi \in Paths(s)$$

$$s \models \forall\varphi \quad \text{iff} \quad \pi \models \varphi \text{ for all } \pi \in Paths(s)$$

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- ① The satisfaction relation \models is defined for **state formulae** by

$s \models a$	iff	$a \in L(s)$
$s \models \neg\Phi$	iff	not $s \models \Phi$
$s \models \Phi \wedge \Psi$	iff	$(s \models \Phi)$ and $(s \models \Psi)$
$s \models \exists\varphi$	iff	$\pi \models \varphi$ for some $\pi \in Paths(s)$
$s \models \forall\varphi$	iff	$\pi \models \varphi$ for all $\pi \in Paths(s)$

- ② For path π , the satisfaction relation \models for **path formulae** is

$\pi \models \bigcirc\Phi$	iff	$\pi[1] \models \Phi$
$\pi \models \Phi \mathbf{U} \Psi$	iff	$\exists j \geq 0. (\pi[j] \models \Psi \wedge (\forall 0 \leq k < j. \pi[k] \models \Phi))$

where for path $\pi = s_0s_1s_2\dots$ and integer $k \geq 0$, $\pi[k] = s_k$

Definition 1 (CTL Semantics for Transition Systems)

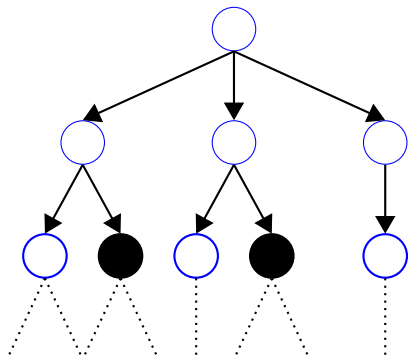
Let $TS = (S, Act, \rightarrow, I, AP, L)$, the satisfaction set $Sat_{TS}(\Phi)$, or $Sat(\Phi)$, for CTL-state formula Φ is defined by:

$$Sat(\Phi) = \{s \in S \mid s \models \Phi\} .$$

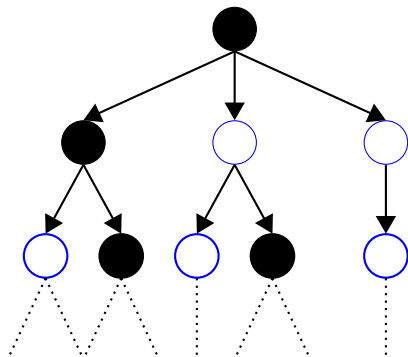
TS satisfies CTL formula Φ if and only if Φ holds in all initial states of TS :

$$TS \models \Phi \quad \text{iff} \quad \forall s_0 \in I. s_0 \models \Phi \quad \text{iff} \quad I \subseteq Sat(\Phi) .$$

2 Semantics

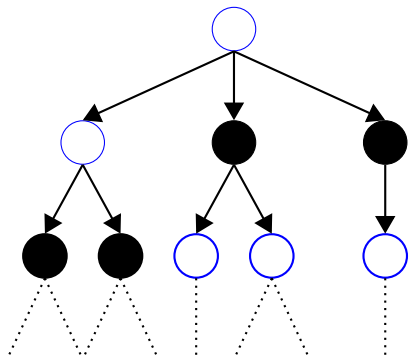


$\exists \blacklozenge \text{black}$

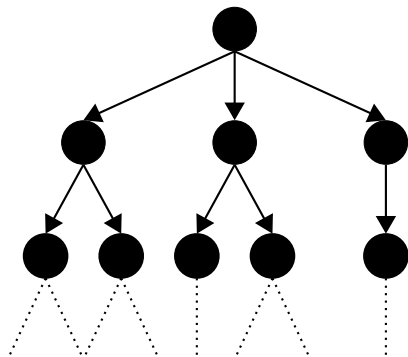


$\exists \blacklozenge \text{black}$

2 Semantics

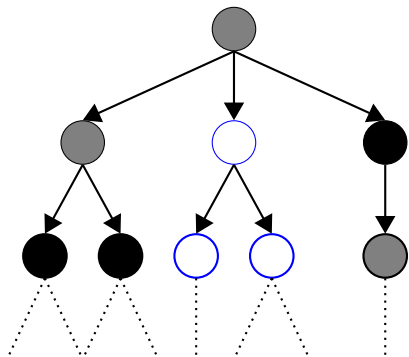


$\forall \diamond \text{black}$

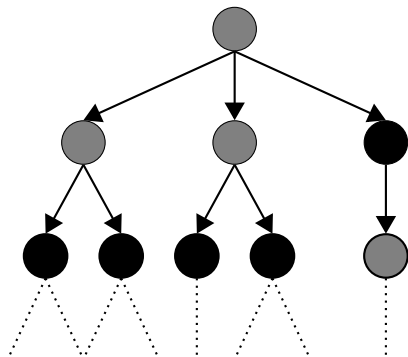


$\forall \square \text{black}$

2 Semantics

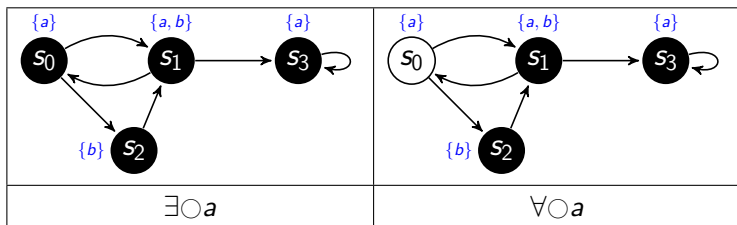
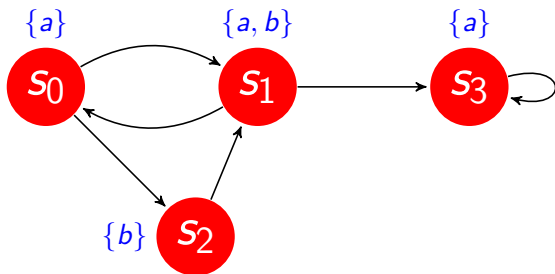


$\exists(\text{gray} \cup \text{black})$



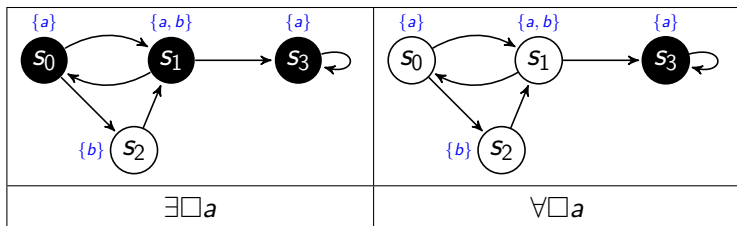
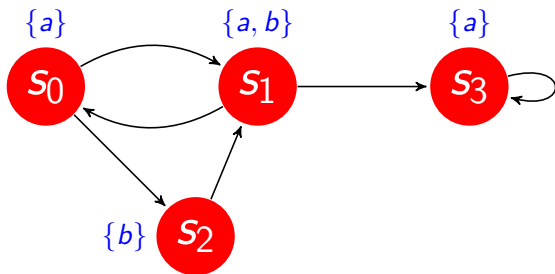
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2 Semantics



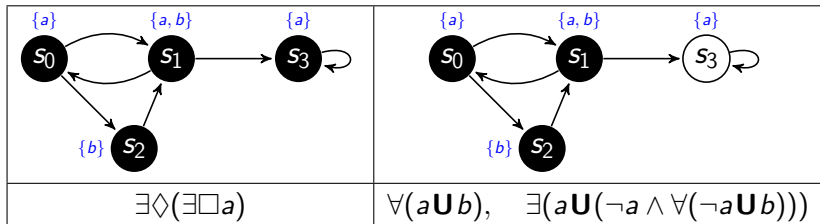
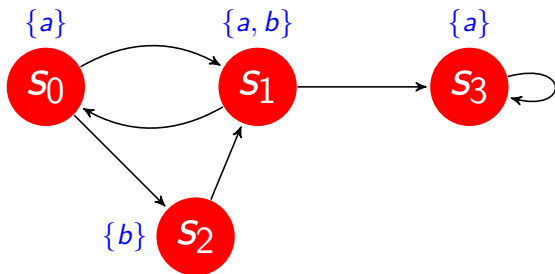
A state is colored black if the formula is valid in that state

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Let TS be a transition system and Φ a CTL formula. Is the following statement correct ?

if $TS \not\models \neg\Phi$ then $TS \models \Phi$

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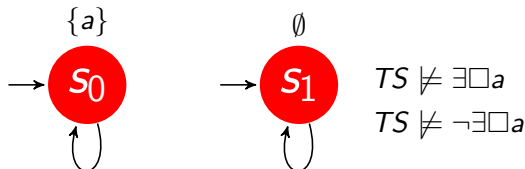
- 1 $TS \models \Phi$ iff $s_0 \models \Phi$ for all initial states s_0 ;
- 2 $TS \not\models \neg\Phi$ iff there exists an initial state s_0 with $s_0 \not\models \neg\Phi$
(iff there exists an initial state s_0 with $s_0 \models \Phi$)

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- 1 $TS \models \Phi$ iff $s_0 \models \Phi$ for all initial states s_0 ;
- 2 $TS \not\models \neg\Phi$ iff there exists an initial state s_0 with $s_0 \not\models \neg\Phi$
(iff there exists an initial state s_0 with $s_0 \models \Phi$)
- 3 transition system TS with 2 initial states:



Weak Until

$$\varphi \mathbf{W} \psi = (\varphi \mathbf{U} \psi) \vee \Box \varphi$$

$$\exists(\Phi \mathbf{W} \Psi) = \neg \forall ((\Phi \wedge \neg \Psi) \mathbf{U} (\neg \Phi \wedge \neg \Psi))$$

$$\forall(\Phi \mathbf{W} \Psi) = \neg \exists ((\Phi \wedge \neg \Psi) \mathbf{U} (\neg \Phi \wedge \neg \Psi))$$

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3 Equivalence of CTL Formulae

Expansion laws:

$$\exists(\Phi \mathbf{U} \Psi) \equiv \Psi \vee (\Phi \wedge \exists \circ \exists(\Phi \mathbf{U} \Psi))$$

$$\forall(\Phi \mathbf{U} \Psi) \equiv \Psi \vee (\Phi \wedge \forall \circ \forall(\Phi \mathbf{U} \Psi))$$

$$\psi \diamond \exists \equiv \psi \vee \exists \circ \psi$$

$$\psi \diamond \forall \equiv \psi \vee \forall \circ \psi$$

$$\exists(\Phi \mathbf{W} \Psi) \equiv \Psi \vee (\Phi \wedge \exists \circ \exists(\Phi \mathbf{W} \Psi))$$

$$\forall(\Phi \mathbf{W} \Psi) \equiv \Psi \vee (\Phi \wedge \forall \circ \forall(\Phi \mathbf{W} \Psi))$$

3 Equivalence of CTL Formulae

duality of \Box and \Diamond :

$$\forall \Box \Phi \equiv \neg \exists \Diamond \neg \Phi$$

$$\forall \Diamond \Phi \equiv \neg \exists \Box \neg \Phi$$

self-duality of \bigcirc :

$$\forall \bigcirc \Phi \equiv \neg \exists \bigcirc \neg \Phi$$

$$\exists \bigcirc \Phi \equiv \neg \forall \bigcirc \neg \Phi$$

duality of **U** and **W**:

$$\forall (\Phi \mathbf{U} \Psi) \equiv \neg \exists ((\Phi \wedge \neg \Psi) \mathbf{W} (\neg \Phi \wedge \neg \Psi))$$

$$\equiv \neg \exists (\neg \Psi) \mathbf{W} (\neg \Phi \wedge \neg \Psi)$$

$$\equiv \neg \exists (\neg \Psi) \mathbf{U} (\neg \Phi \wedge \neg \Psi) \wedge \neg \exists \Box \neg \Psi$$

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4 Normal Forms for CTL

Definition 2 (Existential Normal Form for CTL)

For $a \in AP$, the set of CTL state formulae in *existential normal form* (ENF) is given by

$$\Phi ::= \text{true} \mid a \mid \Phi_1 \wedge \Phi_2 \mid \neg\Phi \mid \exists\bigcirc\Phi \mid \exists(\Phi_1 \mathbf{U}\Phi_2) \mid \exists\Box\Phi$$

Theorem 3 (Existential Normal Form for CTL)

For each CTL formula there exists an equivalent CTL formula in ENF.

Proof: Elimination of the universal path quantifier

$$\begin{aligned}\forall\bigcirc\Phi &\equiv \neg\exists\bigcirc\neg\Phi, \\ \forall(\Phi \mathbf{U}\Psi) &\equiv \neg\exists(\neg\Psi \mathbf{U}(\neg\Phi \wedge \neg\Phi)) \wedge \neg\exists\Box\neg\Psi.\end{aligned}$$

□

The rewrite rule for $\forall\mathbf{U}$ triples the occurrences of Ψ , the translation from CTL to ENF can cause an exponential blowup

4 Normal Forms for CTL

Definition 4 (Positive Normal Form for CTL)

The set of CTL state formulae in positive normal form (PNF) is given by

- 1 State formulae:

$$\Phi ::= \text{true} \mid \text{false} \mid a \mid \neg a \mid \Phi_1 \wedge \Phi_2 \mid \Phi_1 \vee \Phi_2 \mid \exists \varphi \mid \forall \varphi$$

where $a \in AP$;

- 2 Path formulae:

$$\varphi ::= \bigcirc \Phi \mid \Phi_1 \mathbf{U} \Phi_2 \mid \Phi_1 \mathbf{W} \Phi_2$$

4 Normal Forms for CTL

Theorem 5 (Existence of Equivalent PNF Formulae)

For each CTL formula there exists an equivalent CTL formula in PNF.

Proof: “pushing” negations “inside” the formula:

$$\neg \text{true} \equiv \text{false} \quad (1)$$

$$\neg \neg \Phi \equiv \Phi \quad (2)$$

$$\neg(\Phi \wedge \Psi) \equiv \neg\Phi \vee \neg\Psi \quad (3)$$

$$\neg\forall\bigcirc\Phi \equiv \exists\bigcirc\neg\Phi \quad (4)$$

$$\neg\exists\bigcirc\Phi \equiv \forall\bigcirc\neg\Phi \quad (5)$$

$$\neg\forall(\Phi \mathbf{U} \Psi) \equiv \exists((\Phi \wedge \neg\Psi) \mathbf{W}(\neg\Phi \wedge \neg\Psi)) \quad (6)$$

$$\neg\exists(\Phi \mathbf{U} \Psi) \equiv \forall((\Phi \wedge \neg\Psi) \mathbf{W}(\neg\Phi \wedge \neg\Psi)) . \quad (7)$$



For $\forall\mathbf{U}$ and $\exists\mathbf{U}$ the number of occurrences of Ψ (and Φ) is doubled, ...
may be exponentially ...

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5.1 Equivalence of CTL and LTL formulas

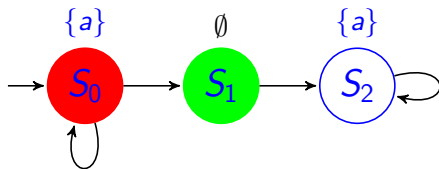
Let Φ be a CTL formula and φ an LTL formula:

$\Phi \equiv \varphi$ iff for all transition systems TS
and all states s in TS :
 $s \models_{CTL} \Phi \Leftrightarrow s \models_{LTL} \varphi$.

Φ	φ
a	a
$\forall \bigcirc a$	$\bigcirc a$
$\forall (a \mathbf{U} b)$	$a \mathbf{U} b$
$\forall \square a$	$\square a$
$\forall \diamond a$	$\diamond a$
$\forall (a \mathbf{W} b)$	$a \mathbf{W} b$
$\forall \square \forall \diamond a$	$\square \diamond a$

5.1 Equivalence of CTL and LTL formulas

Transition system TS :



$$TS \models_{LTL} \diamond \square a$$

$$TS \not\models_{CTL} \forall \diamond \forall \square a$$

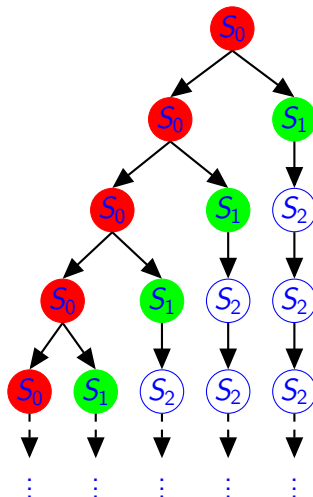


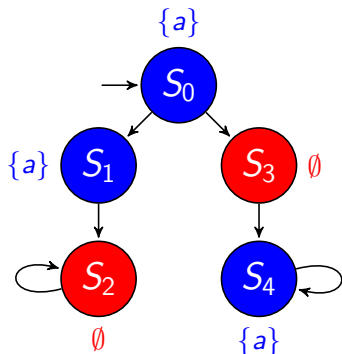
Figure: Computation tree

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5.2 Expressiveness

The expressive powers of LTL and CTL are incomparable

- 1 The CTL formulas $\forall\Diamond(a \wedge \forall\bigcirc a)$, $\forall\Diamond\forall\Box a$ and $\forall\Box\exists\Diamond a$ have no equivalent LTL formula
- 2 The LTL formula $\Diamond\Box a$ has no equivalent CTL formula



$$\begin{aligned} \textcircled{1} \quad & \text{trace}(S_0S_1S_2^\omega) = \{a\}\{a\}\emptyset^\omega \\ & \text{trace}(S_0S_3S_4^\omega) = \{a\}\emptyset\{a\}^\omega \end{aligned}$$

\implies

$$TS \models_{LTL} \Diamond(a \wedge \bigcirc a)$$

$$\textcircled{2} \quad S_0S_1S_2^\omega \not\models_{CTL} \Diamond(a \wedge \forall\bigcirc a)$$

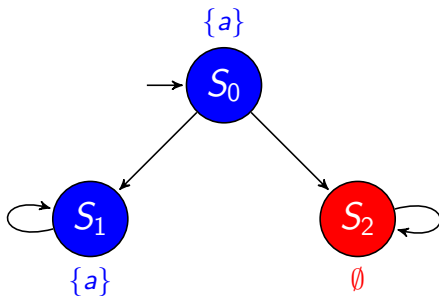
\implies

$$TS \not\models_{CTL} \forall\Diamond(a \wedge \forall\bigcirc a)$$

$$\textcircled{3} \quad \Diamond(a \wedge \bigcirc a) \not\equiv \forall\Diamond(a \wedge \forall\bigcirc a)$$

5.2 Expressiveness

Does $\forall\Diamond(a \wedge \exists\bigcirc a) \equiv \Diamond(a \wedge \bigcirc a)$ hold?



$TS \not\models \Diamond(a \wedge \bigcirc a)$

$TS \models \forall\Diamond(a \wedge \exists\bigcirc a)$

5.2 Expressiveness

Correct?

For each NBA \mathcal{A} there is a CTL formula Φ such that for all transition systems TS :

$$TS \models \Phi \quad \text{iff} \quad \text{Traces}(TS) \subseteq \mathcal{L}_\omega(\mathcal{A})$$

Consider an NBA \mathcal{A} with $\mathcal{L}_\omega(\mathcal{A}) = \text{Words}(\diamond\Box a)$.

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Correct?

If Φ is CTL formula and φ an LTL formula such that $\phi \equiv \varphi$ then $\neg\phi \equiv \neg\varphi$.

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Correct?

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Consider $\Phi = \forall\Box\forall\Diamond a$, $\varphi = \Box\Diamond a$.

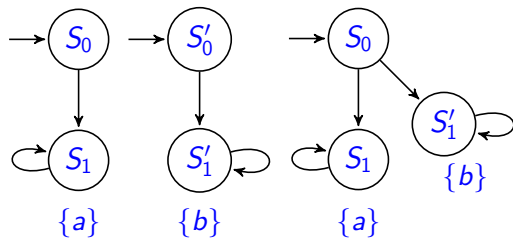
- 1 $\Phi \equiv \varphi$
- 2 no CTL formula that is equivalent to $\neg\varphi \equiv \Diamond\Box\neg a$

5.2 Expressiveness

Correct?

If T_1 and T_2 are trace equivalent TS then for all CTL formulas Φ :

$$T_1 \models \Phi \quad \text{iff} \quad T_2 \models \Phi.$$



CTL formula

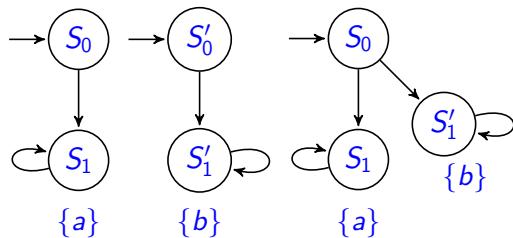
$$\Phi = \exists \bigcirc a \wedge \exists \bigcirc b$$

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CTL formula

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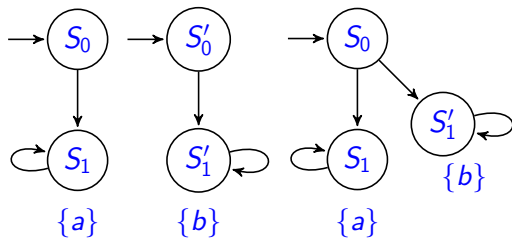
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CTL formula

$$\Phi = \exists \bigcirc a \wedge \exists \bigcirc b$$

- 1 T_1 and T_2 are trace equivalent
- 2 $T_1 \not\models \Phi$
- 3 $T_2 \models \Phi$

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6 CTL Model Checking

CTL-model checking can be performed by a recursive procedure

- 1 calculates the **satisfaction set** for all subformulae of Φ
- 2 and finally **checks** whether all initial states belong to this set

Consider CTL formulae in ENF:

- 1 $\exists \bigcirc$
- 2 $\exists \mathbf{U}$
- 3 $\exists \square$

6 CTL Model Checking

Algorithm 1: CTL model checking (basic idea)

Input: finite transition system TS and CTL formula Φ (both over AP)

Output: $TS \models \Phi$

```
1 forall  $i \leq |\Phi|$  do
2   | forall  $\Psi \in Sub(\Phi)$  with  $|\Psi| = i$  do
3     | compute  $Sat(\Psi)$  from  $Sat(\Psi')$ ;    /* maximal  $\Psi' \in Sub(\Psi)$  */
4     end
5 end
6 return  $I \subseteq Sat(\Phi)$ 
```

$$Sat(\Phi) = \{s \in S \mid s \models \Phi\}$$

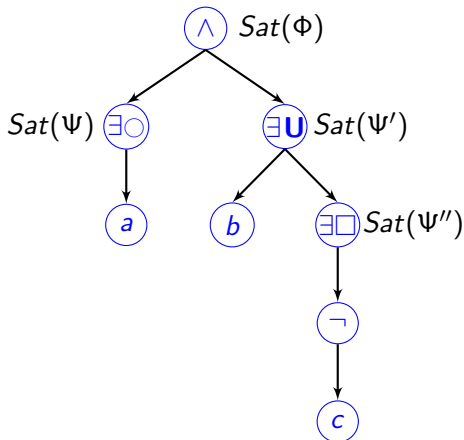
6 CTL Model Checking

The computation of $Sat(\Phi)$: **bottom-up** traversal of the parse tree of Φ :

Consider the following state formula over $AP = \{a, b, c\}$:

$$\Phi = \underbrace{\exists \bigcirc a}_{\Psi} \wedge \underbrace{\exists (b \mathbf{U} \exists \square \neg c)}_{\Psi'}$$

- 1 Ψ and Ψ' are the maximal proper subformulae of Φ
- 2 Ψ'' is a maximal proper subformula of Ψ'



6 CTL Model Checking

Theorem 6 (Characterization of $Sat(\cdot)$ for CTL formulae in ENF)

Let $TS = (S, Act, \rightarrow, I, AP, L)$ be a transition system without terminal states. For all CTL formulae Φ, Ψ over AP it holds that

- 1 $Sat(\text{true}) = S,$

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- 4 $Sat(\neg\Phi) = S \setminus Sat(\Phi)$,

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- 3 $Sat(\Phi \wedge \Psi) = Sat(\Phi) \cap Sat(\Psi),$
- 4 $Sat(\neg\Phi) = S \setminus Sat(\Phi),$
- 5 $Sat(\exists\circ\Phi) = \{s \in S \mid Post(s) \cap Sat(\Phi) \neq \emptyset\},$

6 CTL Model Checking

Theorem 6 (Characterization of $Sat(\cdot)$ for CTL formulae in ENF)

Let $TS = (S, Act, \rightarrow, l, AP, L)$ be a transition system without terminal states. For all CTL formulae Φ, Ψ over AP it holds that

- 1 $Sat(\text{true}) = S$,
- 2 $Sat(a) = \{s \in S \mid a \in L(s)\}$, for any $a \in AP$,
- 3 $Sat(\Phi \wedge \Psi) = Sat(\Phi) \cap Sat(\Psi)$,
- 4 $Sat(\neg\Phi) = S \setminus Sat(\Phi)$,
- 5 $Sat(\exists\bigcirc\Phi) = \{s \in S \mid Post(s) \cap Sat(\Phi) \neq \emptyset\}$,
- 6 $Sat(\exists(\Phi \mathbf{U} \Psi))$ is the **smallest** subset of S , such that (1) $Sat(\Psi) \subseteq T$, and (2) $s \in Sat(\Phi)$ and $Post(s) \cap T \neq \emptyset$ implies $s \in T$,

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- 7 $Sat(\exists\Box\Phi)$ is the **largest** subset T of S , such that (3) $T \subseteq Sat(\Phi)$ and (4) $s \in T$ implies $Post(s) \cap T \neq \emptyset$.

6 CTL Model Checking

$Sat(\exists(\Phi \mathbf{U} \Psi))$ is the **smallest** subset of S , such that

(1) $Sat(\Psi) \subseteq T$, and

(2) $s \in Sat(\Phi)$ and $Post(s) \cap T \neq \emptyset$ implies $s \in T$

Proof: (i) Show that $T = Sat(\exists(\Phi \mathbf{U} \Psi))$ satisfies (1) and (2). From the expansion law

$$\exists(\Phi \mathbf{U} \Psi) \equiv \Psi \vee (\Phi \wedge \exists \bigcirc \exists(\Phi \mathbf{U} \Psi)),$$

it directly follows that T satisfies the properties (1) and (2).

6 CTL Model Checking

Proof (Cont'd): (ii) Show that for **any** T satisfying properties (1) and (2) we have

$$\text{Sat}(\exists(\Phi \mathbf{U} \Psi)) \subseteq T.$$

Let $s \in \text{Sat}(\exists(\Phi \mathbf{U} \Psi))$:

- 1 If $s \in \text{Sat}(\Psi)$, because

$$\text{Sat}(\Psi) \subseteq T,$$

thus $s \in T$.

- 2 If $s \notin \text{Sat}(\Psi)$, there exists a path

$$\pi = s_0 s_1 s_2 \dots$$

starting in $s = s_0$, such that $\pi \models \Phi \mathbf{U} \Psi$.

6 CTL Model Checking

Proof (Cont'd): (ii.2) Let $n > 0$, such that $s_i \models \Phi, 0 \leq i \leq n$, and $s_n \models \Psi$.
Then:

- $s_n \in \text{Sat}(\Psi) \subseteq T$,
- $s_{n-1} \in T$, since $s_n \in \text{Post}(s_{n-1}) \cap T$ and $s_{n-1} \in \text{Sat}(\Phi)$,
- $s_{n-2} \in T$, since $s_{n-1} \in \text{Post}(s_{n-2}) \cap T$ and $s_{n-2} \in \text{Sat}(\Phi)$,
-,
- $s_1 \in T$, since $s_2 \in \text{Post}(s_1) \cap T$ and $s_1 \in \text{Sat}(\Phi)$, and finally
- $s_0 \in T$, since $s_1 \in \text{Post}(s_0) \cap T$ and $s_0 \in \text{Sat}(\Phi)$.

It thus follows that $s = s_0 \in T$.



6 CTL Model Checking

$Sat(\exists\Box\Phi)$ is the **largest** subset T of S , such that

- (1) $T \subseteq Sat(\Phi)$, and
- (2) $s \in T$ implies $Post(s) \cap T \neq \emptyset$

Proof: (i) Show that $T = Sat(\exists\Box\Phi)$ satisfies (1) and (2). From the expansion law

$$\exists\Box\Phi \equiv \Phi \wedge \exists\bigcirc\exists\Box\Phi,$$

it directly follows that T satisfies the properties (1) and (2).

6 CTL Model Checking

Proof (Cont'd): (ii) Show that for any T satisfying properties (1) and (2)

$$T \subseteq \text{Sat}(\exists \square \Phi).$$

Let $T \subseteq S$ satisfy (1) and (2) and $s \in T$:

- $s_0 = s$.
- Since $s_0 \in T$, there exists a state $s_1 \in \text{Post}(s_0) \cap T$.
- Since $s_1 \in T$, there exists a state $s_2 \in \text{Post}(s_1) \cap T$.
-

6 CTL Model Checking

Proof (Cont'd): (ii) Show that for any T satisfying properties (1) and (2)

$$T \subseteq \text{Sat}(\exists \square \Phi).$$

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- Since $s_0 \in T$, there exists a state $s_1 \in \text{Post}(s_0) \cap T$.
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-

Here, property (2) is exploited in every step. From property (1), it follows that

$$s_i \in T \subseteq \text{Sat}(\Phi), \quad i \geq 0.$$

6 CTL Model Checking

Proof (Cont'd): (ii) Show that for any T satisfying properties (1) and (2)

$$T \subseteq \text{Sat}(\exists \square \Phi).$$

Let $T \subseteq S$ satisfy (1) and (2) and $s \in T$:

- $s_0 = s$.
- Since $s_0 \in T$, there exists a state $s_1 \in \text{Post}(s_0) \cap T$.
- Since $s_1 \in T$, there exists a state $s_2 \in \text{Post}(s_1) \cap T$.
-

Here, property (2) is exploited in every step. From property (1), it follows that

$$s_i \in T \subseteq \text{Sat}(\Phi), \quad i \geq 0.$$

Thus, $\pi = s_0 s_1 s_2 \dots$ satisfies $\square \Phi$. It follows that

$$s \in \text{Sat}(\exists \square \Phi), \text{ and then } T \subseteq \text{Sat}(\exists \square \Phi).$$

6 CTL Model Checking

Algorithm 2: Computation of the satisfaction sets

Input: finite transition system TS with state set S , CTL formula Φ in ENF

Output: $Sat(\Phi) = \{s \in S \mid s \models \Phi\}$

```
1 switch  $\Phi$  do
2   | case true do
3     | return  $S$ 
4   | case  $a$  do
5     | return  $\{s \in S \mid a \in L(s)\}$ 
6   | case  $\Phi_1 \wedge \Phi_2$  do
7     | return  $Sat(\Phi_1) \cap Sat(\Phi_2)$ 
8   | case  $\neg\Phi$  do
9     | return  $S \setminus Sat(\Phi)$ 
10  | case  $\exists(\Phi_1 \mathbf{U} \Phi_2)$  do
11    | return  $SFP(\Phi_1, \Phi_2)$ 
12  | case  $\exists\Box\Phi$  do
13    | return  $GFP(\Phi_1, \Phi_2)$ 
14 end
```

Algorithm 3: SFP

Input: CTL formulas Φ_1, Φ_2 in ENF

Output: $Sat(\exists(\Phi_1 \mathbf{U} \Phi_2))$

```
1  $T := Sat(\Phi_2)$ ;  
2 while  $\{s \in Sat(\Phi_1) \setminus T \mid Post(s) \cap T \neq \emptyset\} \neq \emptyset$  do  
3   |   let  $s \in \{s \in Sat(\Phi_1) \setminus T \mid Post(s) \cap T \neq \emptyset\}$ ;  
4   |    $T := T \cup \{s\}$ ;  
5 end  
6 return  $T$ ;
```

6 CTL Model Checking

Algorithm 4: GFP

Input: CTL formulas Φ in ENF

Output: $Sat(\exists\Box\Phi)$

```
1  $T := Sat(\Phi)$ ;  
2 while  $\{s \in T \mid Post(s) \cap T = \emptyset\} \neq \emptyset$  do  
3   |   let  $s \in \{s \in T \mid Post(s) \cap T = \emptyset\}$ ;  
4   |    $T := T \setminus \{s\}$ ;  
5 end  
6 return  $T$ ;
```

6.1 The Until and Existential Always Operator

$Sat(\exists(\Phi \mathbf{U} \Psi))$ is the smallest set $T \subseteq S$, where S is the set of states in TS , such that

- 1 $Sat(\Psi) \subseteq T$ and
- 2 $(s \in Sat(\Phi) \text{ and } Post(s) \cap T \neq \emptyset) \implies s \in T$.

This suggests adopting the following iterative procedure:

- 1 $T_0 = Sat(\Psi)$ and
- 2 $T_{i+1} = T_i \cup \{s \in Sat(\Phi) \mid Post(s) \cap T_i \neq \emptyset\}$.

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6.1 The Until and Existential Always Operator

Algorithm 5: Enumerative backward search for computing $Sat(\exists(\Phi_1 \mathbf{U}\Phi_2))$

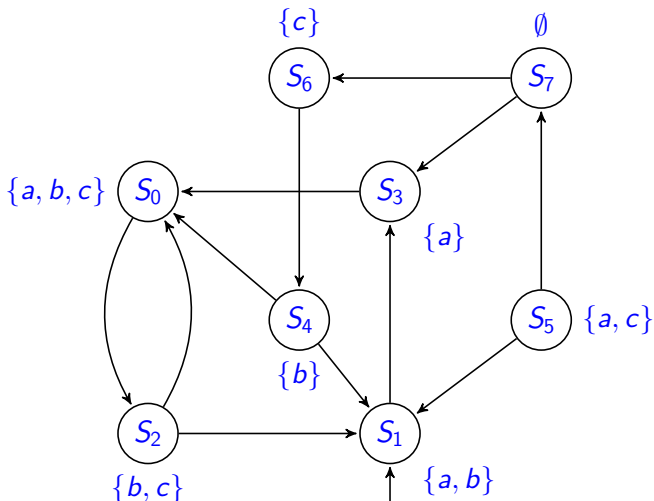
Input: finite transition system TS with state set S and CTL formula $\exists(\Phi_1 \mathbf{U}\Phi_2)$

Output: $Sat(\exists(\Phi_1 \mathbf{U}\Phi_2)) = \{s \in S \mid s \models \exists(\Phi_1 \mathbf{U}\Phi_2)\}$

```
1  $E := Sat(\Phi_2); T := E;$ 
2 while  $E \neq \emptyset$  do
3   | let  $s' \in E;$ 
4   |  $E := E \setminus \{s'\};$ 
5   | foreach  $s \in Pre(s')$  do
6   |   | if  $s \in Sat(\Phi_1) \setminus T$  then
7   |   |   |  $E := E \cup \{s\};$ 
8   |   |   |  $T := T \cup \{s\};$ 
9   |   | end
10  | end
11 end
12 return  $T;$ 
```

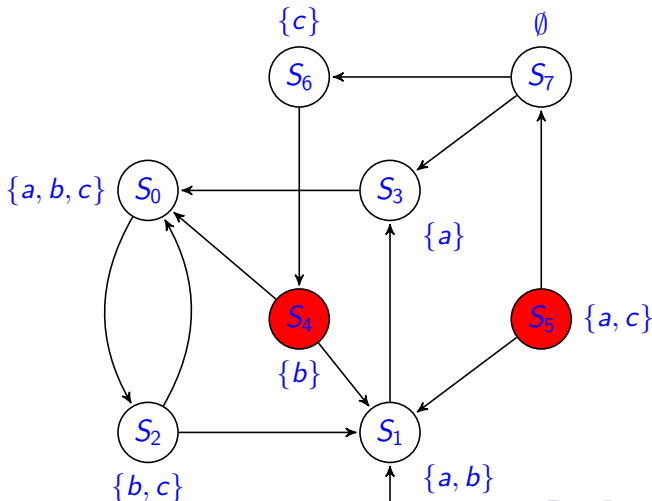
6.1 The Until and Existential Always Operator

Example of backward search for $\exists(\text{true} \mathbf{U}(a = c) \wedge (a \neq b))$



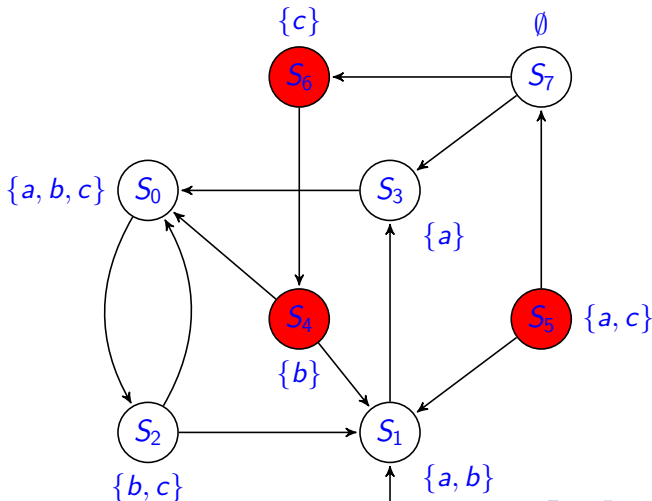
6.1 The Until and Existential Always Operator

all states in the set T are colored red, we select and delete S_5 from E , but as $Pre(S_5) = \emptyset$, T remains unaffected, $T = \{S_4, S_5\}, E = \{S_4\}$



6.1 The Until and Existential Always Operator

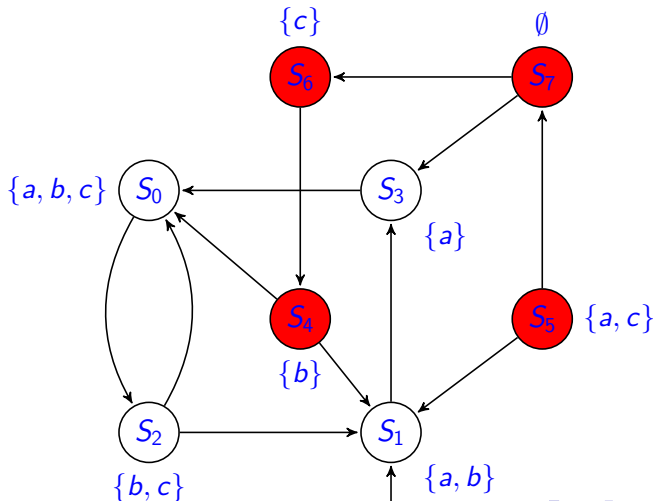
On considering $S_4 \in E$, $Pre(S_4) = \{S_6\}$ is added to T (and E),
 $T = \{S_4, S_5, S_6\}$, $E = \{S_6\}$



6.1 The Until and Existential Always Operator

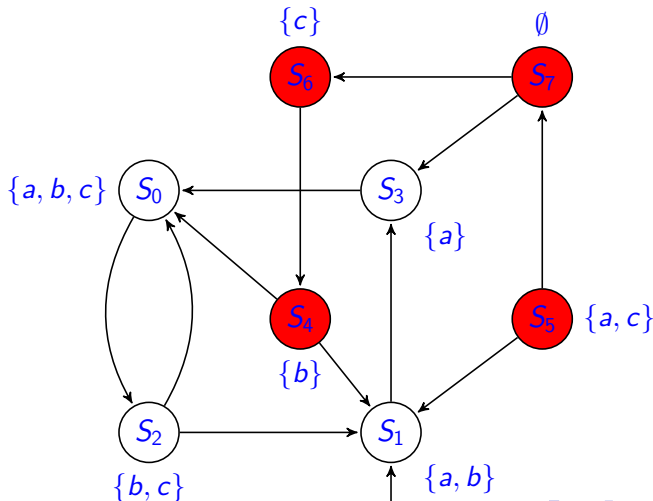
During the next iteration, the only predecessor of S_6 is added,

$$T = \{S_4, S_5, S_6, S_7\}, E = \{S_7\}$$



6.1 The Until and Existential Always Operator

After the fourth iteration, the algorithm terminates as there are no new predecessors of Φ -states encountered, $T = \{S_4, S_5, S_6, S_7\}$, $E = \{\}$



6.1 The Until and Existential Always Operator

$Sat(\exists\Box\Phi)$ is the largest set $T \subseteq S$ satisfying

- 1 $T \subseteq Sat(\Phi)$ and
- 2 $s \in T$ implies $T \cap Post(s) \neq \emptyset$

The basic idea is to compute $Sat(\exists\Box\Phi)$ by means of the iteration

- 1 $T_0 = Sat(\Phi)$ and
- 2 $T_{i+1} = T_i \cap \{s \in Sat(\Phi) \mid Post(s) \cap T_i \neq \emptyset\}$

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6.1 The Until and Existential Always Operator

Algorithm 6: Enumerative backward search to compute $Sat(\exists\Box\Phi)$

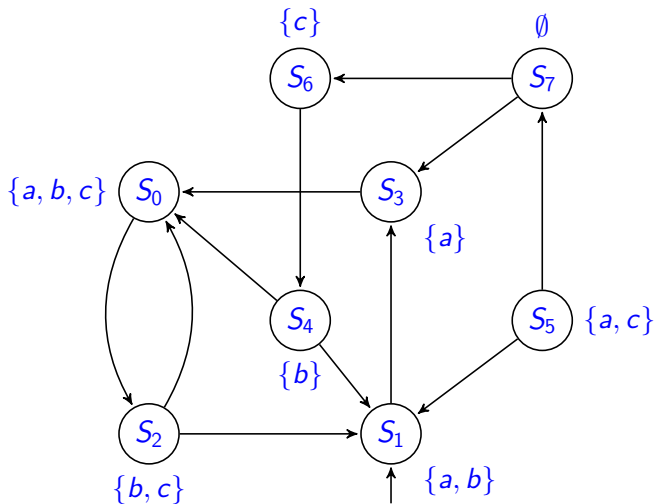
Input: finite transition system TS with state set S and CTL formula $\exists\Box\Phi$

Output: $Sat(Sat(\exists\Box\Phi)) = \{s \in S \mid s \models \exists\Box\Phi\}$

```
1  $E := S \setminus Sat(\Phi); T := Sat(\Phi);$ 
2 foreach  $s \in Sat(\Phi)$  do  $count[s] := |Post(s)|;$ 
3 while  $E \neq \emptyset$  do
4   |  $let\ s' \in E;$ 
5   |  $E := E \setminus \{s'\};$ 
6   | foreach  $s \in Pre(s')$  do
7   |   | if  $s \in T$  then
8   |   |   |  $count[s] := count[s] - 1;$ 
9   |   |   | if  $count[s] = 0$  then  $T := T \setminus \{s\}; E := E \cup \{s\};$ 
10  |   |   | end
11  |   | end
12  | end
13 return  $T;$ 
```

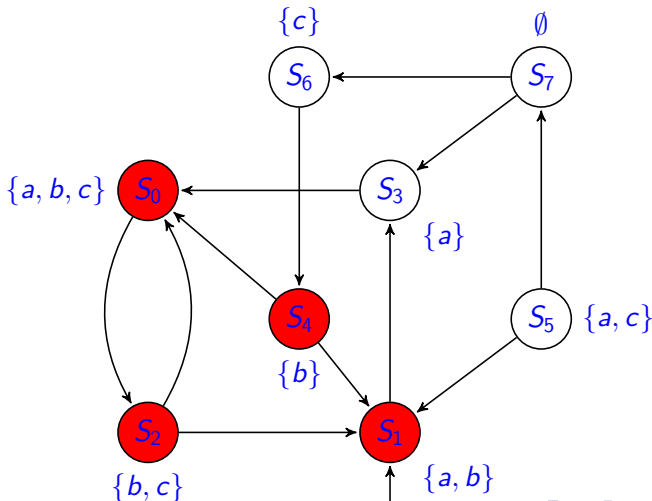
6.1 The Until and Existential Always Operator

Consider the formula $\exists \square b$ for TS :



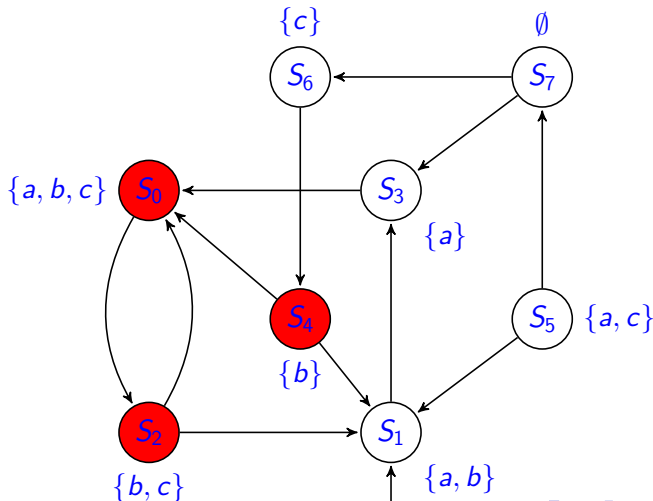
6.1 The Until and Existential Always Operator

$T_0 = \{S_0, S_1, S_2, S_4\}$ and $E = \{S_3, S_5, S_6, S_7\}$ and
 $count = \{S_0 \mapsto 1, S_1 \mapsto 1, S_2 \mapsto 2, S_4 \mapsto 2\}$



6.1 The Until and Existential Always Operator

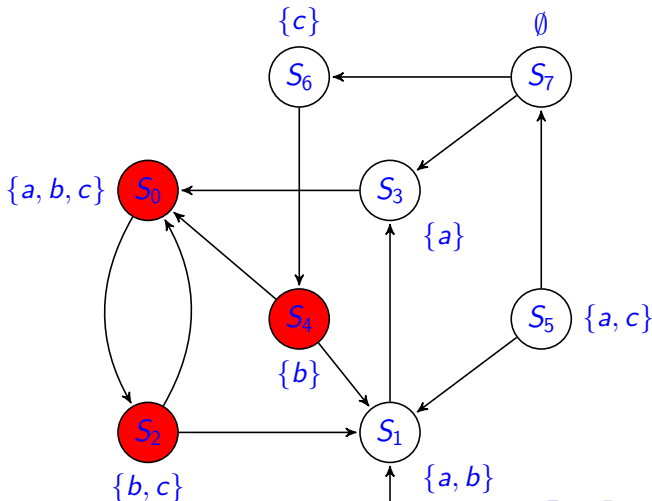
$S_3 \in E$ is selected in the first iteration. $T_1 = \{S_0, S_2, S_4\}$,
 $E = \{S_1, S_5, S_6, S_7\}$, $count = \{S_0 \mapsto 1, S_2 \mapsto 2, S_4 \mapsto 2\}$



6.1 The Until and Existential Always Operator

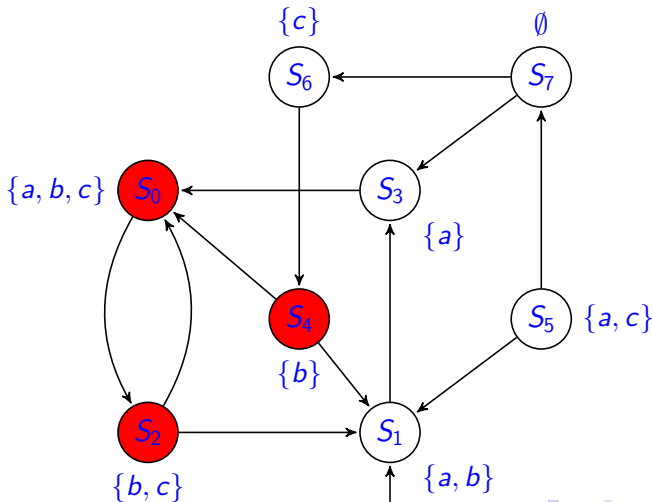
S_6 and S_7 are selected in the second and third iteration.

$T_2 = \{S_0, S_2, S_4\}$, $E = \{S_1, S_5\}$, $count = \{S_0 \mapsto 1, S_2 \mapsto 2, S_4 \mapsto 2\}$



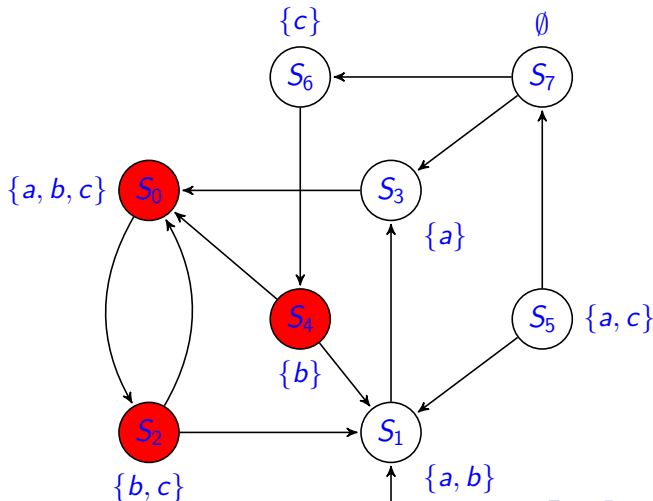
6.1 The Until and Existential Always Operator

S_1 is selected. $Pre(S_1) \cap T_2 = \{S_2, S_4\}$. $T_3 = \{S_0, S_2, S_4\}$, $E = \{S_5\}$,
 $count = \{S_0 \mapsto 1, S_2 \mapsto 1, S_4 \mapsto 1\}$



6.1 The Until and Existential Always Operator

At last, S_5 is selected. $Pre(S_5) = \emptyset$. $T_4 = \{S_0, S_2, S_4\}$, $E = \emptyset$,
 $count = \{S_0 \mapsto 1, S_2 \mapsto 1, S_4 \mapsto 1\}$.



6.1 The Until and Existential Always Operator

A possibility to compute $Sat(\exists\Box\Phi)$ is to only consider the Φ -states of TS and ignore all $\neg\Phi$ -states

Another Way to Compute $Sat(\exists\Box\Phi)$

For $TS = (S, Act, \rightarrow, I, AP, L)$, let

$$TS[\Phi] = (S', Act, \rightarrow', I', AP, L')$$

in which, $S' = Sat(\Phi)$, $\rightarrow' = \rightarrow \cap (S' \times Act \times S')$, $I' = I \cap S'$ and $L'(s) = L(s)$ for all $s \in S'$.

- 1 All states in each nontrivial **strongly connected components** of $TS[\Phi]$ satisfy $\exists\Box\Phi$
- 2 All states in $TS[\Phi]$ that can **reach such SCC** satisfy $\exists\Box\Phi$

A **nontrivial** SCC is an SCC that contains at least one transition.

6.1 The Until and Existential Always Operator

Theorem 7

For state s in transition system TS and CTL formula Φ :

$s \models \exists \square \Phi$ iff $s \models \Phi$ and there is a nontrivial SCC in $TS[\Phi]$ reachable from s .

Proof: \Rightarrow : Suppose $s \models \exists \square \Phi$.



According to the definition of $TS[\Phi]$, s is a state in $TS[\Phi]$.



$\pi =$ path in TS starting in s and $\pi \models \square \Phi$



TS is finite, π contains a circle $c = \{s_1, \dots, s_k\}$



c is a SCC or contained in some SCC in $TS[\Phi]$



s can reach such SCC

6.1 The Until and Existential Always Operator

Proof: \Leftarrow :

Suppose s is a state in $TS[\Phi]$ and an SCC in $TS[\Phi]$ reachable from s

\Downarrow

s' be a state in such SCC, infinite path $\pi = (s' \rightsquigarrow s')^\omega \models \Box\Phi$

\Downarrow

$\pi' = (s \rightsquigarrow_{s'} \pi) \models \Box\Phi$

\Downarrow

$s \models \exists\Box\Phi$

6.2 Complexity

- 1 Suppose the sets of predecessors $Pre(\cdot)$ are represented as linked lists in Algorithm-5 and Algorithm-6 (Time complexity: $O(N + K)$).
- 2 The computation of $Sat(\Phi)$ is a bottom-up traversal over the **parse tree** of Φ and linear in $|\Phi|$

Theorem 8 (Time Complexity of CTL Model Checking)

For transition system TS with N states and K transitions, and CTL formula Φ , the CTL model-checking problem $TS \models \Phi$ can be determined in time $O((N + K) \cdot |\Phi|)$.

6.2 Complexity

NP-complete

A decision problem C is **NP-complete** if:

- 1 C is in NP (that a candidate solution to C can be verified in polynomial time), and
- 2 Every problem in NP is reducible to C in polynomial time

Hamiltonian path

Consider the NP-complete problem of finding a Hamiltonian path in an arbitrary, connected, directed graph G

- 1 $G = (V, E)$
- 2 $V = \{v_1, \dots, v_n\}$
- 3 $E \subseteq V \times V$

A **Hamiltonian path** is a (finite) path through the graph G which visits each state exactly once.

6.2 Complexity

From G to TS

From graph G , $TS(G)$ and CTL formula Φ_n can be derived, such that

G contains a Hamiltonian path if and only if $TS \not\models \neg\Phi_n$

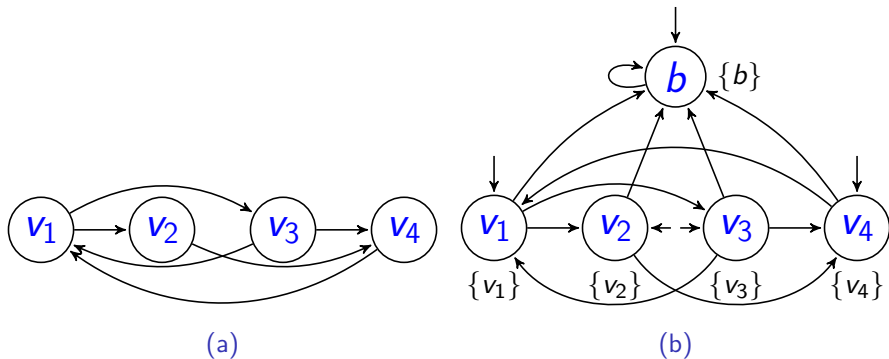
- 1 $TS = (V \cup \{b\}, \{\tau\}, \rightarrow, V, V, L)$, the set initial states and set of atomic propositions are represented by V
- 2 $L(v_i) = \{v_i\}$, $L(b) = \emptyset$
- 3 The transition relation \rightarrow is defined by

$$\frac{(v_i, v_j) \in E}{v_i \xrightarrow{\tau} v_j} \quad \text{and} \quad \frac{v_i \in V \cup \{b\}}{v_i \xrightarrow{\tau} b}$$

- 4 State b is used to ensure that TS has no terminal states

6.2 Complexity

Example of encoding the Hamiltonian path problem as a transition system



6.2 Complexity

Let Φ_n be defined as follows

$$\Phi_n = \bigvee_{(i_1, \dots, i_n) \in P_m[1, \dots, n]} \Psi(v_{i_1}, v_{i_2}, \dots, v_{i_n})$$

- 1 $\Psi(v_{i_1}, v_{i_2}, \dots, v_{i_n})$ is a CTL formula that is satisfied if and only if $v_{i_1}, v_{i_2}, \dots, v_{i_n}$ is a Hamiltonian path in G .
- 2 The formulae $\Psi(v_{i_1}, v_{i_2}, \dots, v_{i_n})$ are inductively defined as follows

$$\begin{aligned}\Psi(v_i) &= v_i \\ \Psi(v_{i_1}, v_{i_2}, \dots, v_{i_n}) &= v_{i_1} \wedge \exists \circ \Psi(v_{i_2}, \dots, v_{i_n}) \quad \text{if } n > 1\end{aligned}$$

6.2 Complexity

An example of an instantiation of Φ_n is

$$\Phi_2 = (v_1 \wedge \exists \circ v_2) \vee (v_2 \wedge \exists \circ v_1)$$

and

$$\begin{aligned} \Phi_3 = & (v_1 \wedge \exists \circ (v_2 \wedge \exists \circ v_3)) \vee (v_1 \wedge \exists \circ (v_3 \wedge \exists \circ v_2)) \\ & \wedge (v_2 \wedge \exists \circ (v_1 \wedge \exists \circ v_3)) \vee (v_2 \wedge \exists \circ (v_3 \wedge \exists \circ v_1)) \\ & \wedge (v_3 \wedge \exists \circ (v_1 \wedge \exists \circ v_2)) \vee (v_3 \wedge \exists \circ (v_2 \wedge \exists \circ v_1)). \end{aligned}$$

6.2 Complexity

$$\text{Sat}(\Psi(v_{i_1}, v_{i_2}, \dots, v_{i_n})) = \begin{cases} \{v_{i_1}\} & \text{if } v_{i_1}, \dots, v_{i_n} \text{ is a Hamiltonian path in } G \\ \emptyset & \text{otherwise.} \end{cases}$$

$TS \not\models \neg\Phi_n$

iff there is an initial state s of TS for which $s \not\models \neg\Phi_n$

iff there is an initial state s of TS for which $s \models \Phi_n$

iff $\exists v$ in G and a permutation i_1, \dots, i_n of $1, \dots, n$
with $v \in \text{Sat}(\Psi(v_{i_1}, v_{i_2}, \dots, v_{i_n}))$

iff $\exists v$ in G and a permutation i_1, \dots, i_n of $1, \dots, n$, such that
 $v = v_{i_1}$ and v_{i_1}, \dots, v_{i_n} is a Hamiltonian path in G

iff G has a Hamiltonian path

6.2 Complexity

Stirling's formula

$$n! \approx \sqrt{2\pi n} \cdot \left(\frac{n}{e}\right)^n \cdot \left(1 + \frac{1}{12n}\right)$$

- 1 The size of Φ_n is exponential in the number of vertices in the graph.
- 2 This does not prove that there does not exist an equivalent, but shorter, CTL formula which describes the Hamiltonian path problem.
- 3 Shorter formalizations in CTL cannot be expected, since the CTL model-checking problem is polynomially solvable whereas the Hamiltonian path problem is NP-complete
- 4 Thus, if $P = NP$ then shorter ($poly(n)$) CTL formula can be found